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WARNING!

This product contains a chemical known to the state of California to cause cancer and birth defects or other reproductive harm.

INTEGY INC. assumes no liability for the use or misuse of this product or damages incurred to person or property by the use or misuse of chargers, batteries, electronic speed controllers, or other electronics that are used in conjunction with these products.

Due to the nature of the use and misuse of these products, Integy Inc. only warranties that this product meets all factory specs at the time of purchase and is free from any manufacturing defects. No other warranty is implied. INTEGY INC., the point of purchase, any dealer/distributor, their employees or owners will assume no responsibility for any damages or injuries to property or person that may occur. By purchasing any of these items, the consumer/buyer/user assumes all liability and takes full responsibility for usage and the results of these items.

Because we cannot control the way lithium batteries will be used, charged, discharged or stored after purchase, INTEGY INC. offers no warranty on lithium battery packs other than the pack working correctly upon first charge. Lithium battery pack swelling, lithium packs damaged through usage, and/or short-circuited packs will not be covered under warranty. Use lithium battery pack(s) at your own risk.

INDI MOTOR DYNOv2 (0-9V 13A:MAX) #E2028

TEAM INTEGY TECHNOLOGIES, INC.

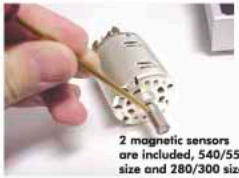
online catalog www.integy.com

INDI DynoV2 operate with most 12VDC power supply with at least 10A capacity. Excessive input voltage can severely damage this unit.

1. Connect Dyno to a 12VDC power source

2. Select Menu 1 to run motor

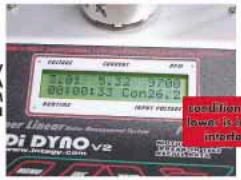
3. Adjust the voltage output to 3.0



4. Install the correct size magnetic sensor

5. Connect motor with correct polarity

6. Press Enter to start motor run



7. Here is the data screen during motor run

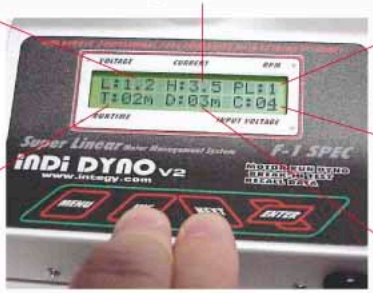
8. Press enter to stop & save data

9. Select Menu 2 to break in motor

10. Use the INC and NEXT keya to set parameters

11. Select Menu 3 to view saved data

12. Select Menu 4 to delete all 12 data slots



Tuning tip: try to tune stock motor for the highest possible rpm with the lowest interference. Commutator cutting & slow break-in speed can usually bring the interference level even lower.

A good test run speed is usually 3.0V for stock and 19T motors, the low voltage reduce brush and commutator wear; excessive brush arcing may occur at higher voltage level. Modified motors can handle higher voltage and you can test rpm using whatever voltage reference point you choose. However, excessive rpm under no-load condition can damage low turn motors such as 7 to 9 turns.